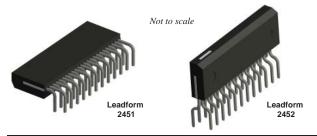




Features and Benefits

- Built-in pre-drive IC
- MOSFET power element
- CMOS compatible input (5 V)
- High-side gate driver using bootstrap circuit or floating power supply
- Built-in protection circuit for controlling power supply voltage drop
- Built-in overtemperature detection circuit (TD)
- Output of fault signal during operation of protection circuits
- Output current 2.5 A
- Small SIP (SLA 24-pin)

Packages: Power SIP



Description

The SMA6853M inverter power module (IPM) device provides a robust, highly-integrated solution for optimally controlling 3-phase motor power inverter systems and variable speed control systems used in energy-conserving designs to drive motors of residential and commercial appliances. These ICs take 230 VAC input voltage, and 2.5 A (continuous) output current. They can withstand voltages of up to 500 V (MOSFET breakdown voltage).

The SLA6800M power package includes an IC with all of the necessary power elements (six MOSFETs), pre-driver ICs (two), and flyback diodes (six), needed to configure the main circuit of an inverter. This enables the main circuit of the inverter to be configured with fewer external components than traditional designs.

Applications include residential white goods (home applications) and commercial appliance motor control:

- · Air conditioner fan
- Refrigerator compressor
- · Dishwasher pump

Functional Block Diagram

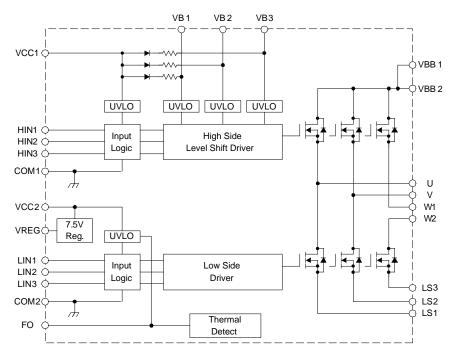


Figure 1. Driver block diagram

High Voltage 3-Phase Motor Driver

Selection Guide

		MOSFET Breakdown	Output Current		
Part Number Packing		Voltage, V _{DSS} (min) (V)	Continuous, I _O (max) Pulsed, I _{OP} (n (A) (A)		
SMA6853M	18 pieces per tube	500	2.5	5	

Absolute Maximum Ratings, valid at $T_A = 25$ °C

Characteristic	Symbol	Remarks	Rating	Unit
MOSFET Breakdown Voltage	V _{DSS}	$V_{CC} = 15 \text{ V}, I_D = 100 \mu\text{A}, V_{IN} = 0 \text{ V}$	500	V
Logic Supply Voltage	V _{CC}	Between VCC and COM	20	V
Bootstrap Voltage	V _{BS}	Between VB and HS (U,V, and W phases)	20	V
Output Current, Continuous	Io		2.5	Α
Output Current, Pulsed	I _{OP}	PW ≤ 100 µs, duty cycle = 1%	5	А
Output Current for Regulator	I _{REG}		35	mA
Input Voltage	V _{IN}		-0.5 to 7	V
Allowable Power Dissipation	P _D	$T_C = 25^{\circ}C$	28	W
Thermal Resistance (Junction to Case)	R _{eJC}	All elements operating	4.46	°C/W
Thermal Resistance (Junction to Ambient)	$R_{\theta JA}$	All elements operating	31.25	°C/W
Case Operating Temperature	T _{COP}		-20 to 100	°C
Junction Temperature (MOSFET)	TJ		150	°C
Storage Temperature	T _{stg}		-40 to 150	°C

Recommended Operating Conditions

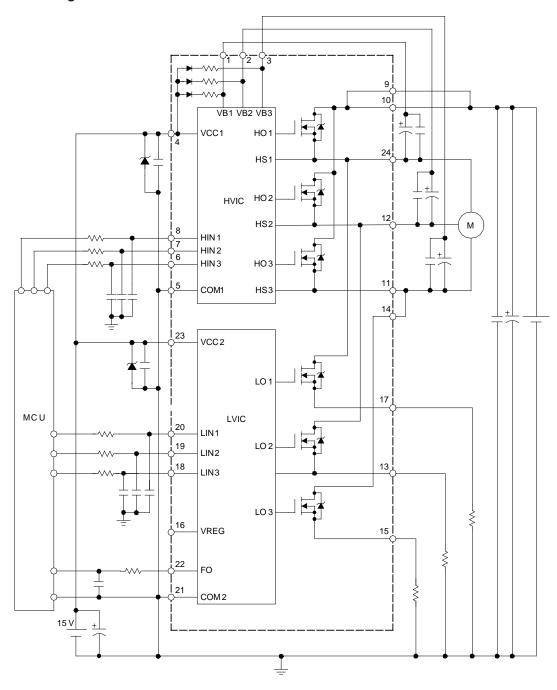
•	•					
Characteristic	Symbol	Remarks	Min.	Тур.	Max.	Units
Main Supply Voltage	V _{BB}	Between VBB and LS	_	280	400	V
Logic Supply Voltage	V _{CC}	Between VCC and COM	13.5	_	16.5	V
Minimum Input Pulse	T _W (min)		0.5	-	_	μs
Dead Time	t _{dead}		1.5	-	_	μs
Junction Temperature	TJ		_	-	125	°C

All performance characteristics given are typical values for circuit or system baseline design only and are at the nominal operating voltage and an ambient temperature, T_A , of 25°C, unless otherwise stated.





Typical Application Diagram



NOTE:

- All of the input pins are connected to GND with internal pull-down resistors rated at $100 \text{ k}\Omega$, however, an external pull-down resistor may be required to secure stable condition of the inputs if high impedance conditions are applied to them.
- The external electrolytic capacitors should be placed as close to the IC as possible, in order to avoid malfunctions from
 external noise interference. Put a ceramic capacitor in parallel with the electrolytic capacitor if further reduction of noise
 susceptibility is necessary.





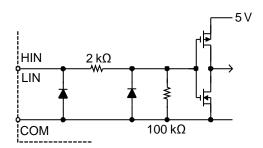
High Voltage 3-Phase Motor Driver

ELECTRICAL CHARACTERISTICS, valid at T_A =25°C, unless otherwise noted

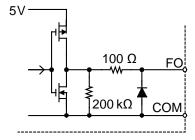
Characteristics	Symbol	Conditions	Min	Тур	Max	Units
Logic Supply Voltage	V _{CC}	Between VCC and COM	13.5	15	16.5	V
Logic Supply Current	I _{CC}	V _{CC} = 15 V, I _{REG} = 0 A	-	4	6	mA
land Valence	V _{IH}	V _{CC} = 15 V, output on	_	2.0	2.5	V
Input Voltage	V _{IL}	$V_{CC} = 15 \text{ V}$, output off	1.0	1.5	_	V
Input Voltage Hysteresis	V _{Ihys}	V _{CC} = 15 V	_	0.5	_	V
Input Current	I _{IH}	High side, $V_{CC} = 15 \text{ V}$, $V_{IN} = 5 \text{ V}$	_	50	100	μA
Input Current	I _{IL}	Low side, $V_{CC} = 15 \text{ V}$, $V_{IN} = 0 \text{ V}$	_	_	2	μA
	V _{UVHL}	High aids hetween VD and H V ar W	9.0	10.0	11.0	V
	V _{UVHH}	High side, between VB and U, V, or W	9.5	10.5	11.5	V
Lindonyoltogo Look Out	V _{UVHhys}	High side, hysteresis	_	0.5	_	V
Undervoltage Lock Out	V _{UVLL}	Low side between VCC and COM	10.0	11.0	12.0	V
	V _{UVLH}	Low side, between VCC and COM	10.5	11.5	12.5	V
	V _{UVLhys}	Low side, hysteresis	_	0.5	_	V
EO Terminal Output Valtage	V _{FOL}	V 45V	0	_	1.0	V
FO Terminal Output Voltage	V _{FOH}	$V_{CC} = 15 \text{ V}$	4.0	-	5.5	V
Overtemperature Detection Threshold	T _{DH}	V _{CC} = 15 V, no heatsink	130	145	160	°C
Temperature (activation and	T _{DL}		105	120	135	°C
deactivation)	T _{Dhys}		15	25	35	°C
Output Voltage for Regulator	V_{REG}	$I_{REG} = 35 \text{ mA}, T_C = -20^{\circ}\text{C to } 100^{\circ}\text{C}$	6.75	7.5	8.25	V
Bootstrap Diode Leakage Current	I _{LBD}	V _R = 500 V	_	5	10	μA
Bootstrap Diode Forward Voltage	V_{FBD}	$I_F = 0.15 A$	_	1.1	1.3	V
Bootstrap Diode Series Resistor	R _{BD}		17.6	22	26.4	Ω
MOSFET Breakdown Voltage	V _{DSS}	$V_{CC} = 15 \text{ V}, I_D = 100 \mu\text{A}, V_{IN} = 0 \text{ V}$	500	_	_	V
MOSFET Leakage Current	I _{DSS}	$V_{CC} = 15 \text{ V}, V_{DS} = 500 \text{ V}, V_{IN} = 0 \text{ V}$	_	_	100	μA
MOSFET On State Resistance	R _{DS(on)}	$V_{CC} = 15 \text{ V}, I_D = 1.5 \text{ A}, V_{IN} = 5 \text{ V}$	_	2.0	2.4	Ω
MOSFET Diode Forward Voltage	V _{SD}	$V_{CC} = 15 \text{ V}, I_{SD} = 1.5 \text{ A}, V_{IN} = 0 \text{ V}$	_	1.0	1.5	V
MOSFET Diode Recovery Time	t _{rr}	$I_{SD} = 1.5 \text{ A}, \text{ di/dt} = 100 \text{ A/}\mu\text{s}$	_	75	_	ns
Switching Time, High Side	t _{dH(on)}	V - 200 V V - 45 V I - 4 5 A 0 V C V C 5 V	_	660	-	ns
	t _{rH}		_	100	_	ns
	t _{dH(off)}		_	540	-	ns
	t _{fH}		_	50	-	ns
	t _{dL(on)}	$V_{BB} = 300 \text{ V}, V_{CC} = 15 \text{ V}, I_{D} = 1.5 \text{ A}, 0 \text{ V} \le V_{IN} \le 5 \text{ V}$	_	730	_	ns
Switching Time Low Side	t _{rL}		_	130	_	ns
Switching Time, Low Side	t _{dL(off)}		_	540	_	ns
	t _{fL}		_	40	_	ns







HINx and LINx Terminals Internal Equivalent Circuit

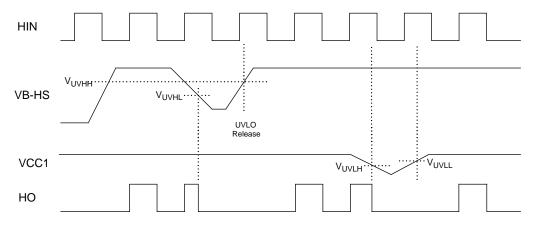


FO Terminal Internal Equivalent Circuit



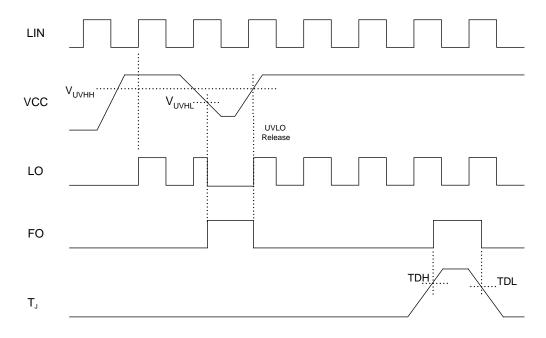


High Side Driver Input/Output Timing Diagrams



After UVLO is released, IC operation is started by the first rising edge of input

Low Side Driver Input/Output Timing Diagrams



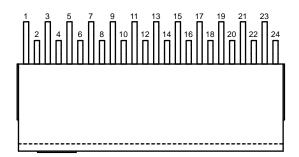
After UVLO is released, IC operation is started by the first rising edge of input

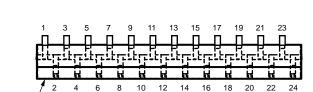


Pin-out Diagrams

Chamfer Side







Leadform 2452

Chamfer on Opposite Side

Terminal List Table

Number	Name	Function
1	VB1	High side bootstrap terminal (U phase)
2	VB2	High side bootstrap terminal (V phase)
3	VB3	High side bootstrap terminal (W phase)
4	VCC1	High side logic supply voltage
5	COM1	High side logic GND terminal
6	HIN3	High side input terminal (W phase)
7	HIN2	High side input terminal (V phase)
8	HIN1	High side input terminal (U phase)
9	VBB1	Main supply voltage 1 (connect to VBB2 externally)
10	VBB2	Main supply voltage 2 (connect to VBB1 externally)
11	W1	Output of W phase (connect to W2 externally)
12	V	Output of V phase
13	LS2	Source terminal of V phase
14	W2	Output of W phase (connect to W1 externally)
15	LS3	Source terminal of W phase
16	VREG	Internal regulator output terminal
17	LS1	Source terminal of U phase
18	LIN3	Low side input terminal (W phase)
19	LIN2	Low side input terminal (V phase)
20	LIN1	Low side input terminal (U phase)
21	COM2	Low side GND terminal
22	FO	Overtemperature detection fault-signal output terminal
23	VCC2	Low side logic supply voltage
24	U	Output of U phase

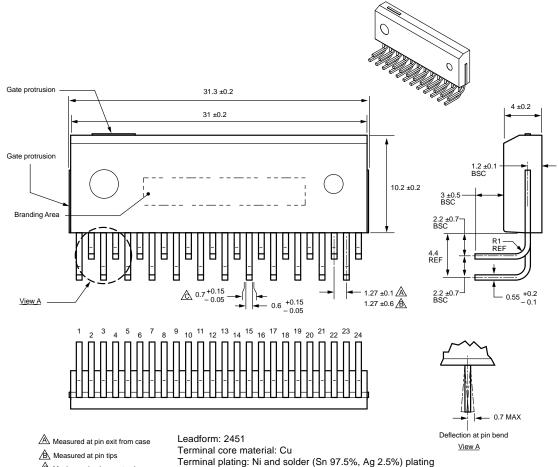




Package Outline Drawing

Leadform 2451

Dual rows, 24 alternating pins; pins bent 90° for horizontal case mounting; pin #1 in outer row



A Maximum dambar protrusion

Case material: Epoxy resin

Dimensions in millimeters

Branding codes (exact appearance at manufacturer discretion):

1st line, lot: **YMDDT**

Where: Y is the last digit of the year of manufacture

M is the month (1 to 9, O, N, D)

DD is the date

T is the tracking letter

2nd line, type: SMA6861M



Leadframe plating Pb-free. Device composition complies with the RoHS directive.

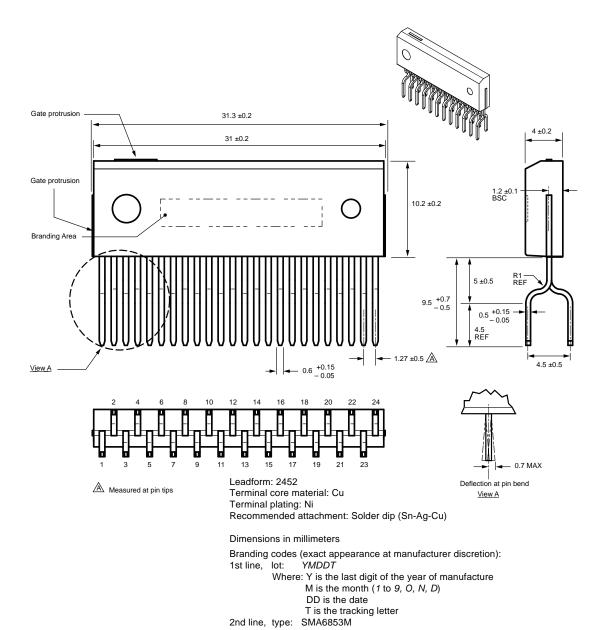




Package Outline Drawing

Leadform 2452

Dual rows, 24 alternating pins; vertical case mounting; pin #1 opposite chamfer side





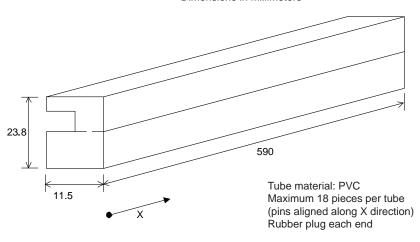
Leadframe plating Pb-free. Device composition complies with the RoHS directive.

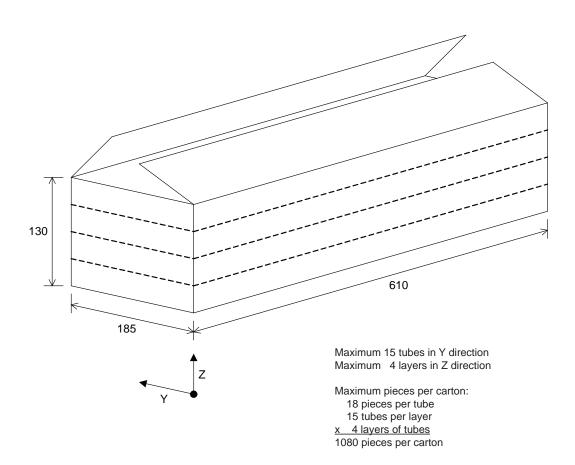




Packing Specification Leadform 2451

Dimensions in millimeters



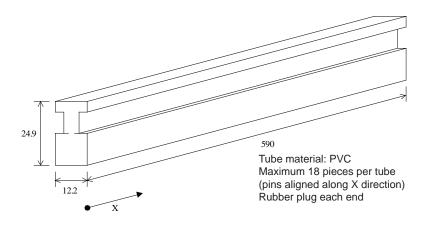


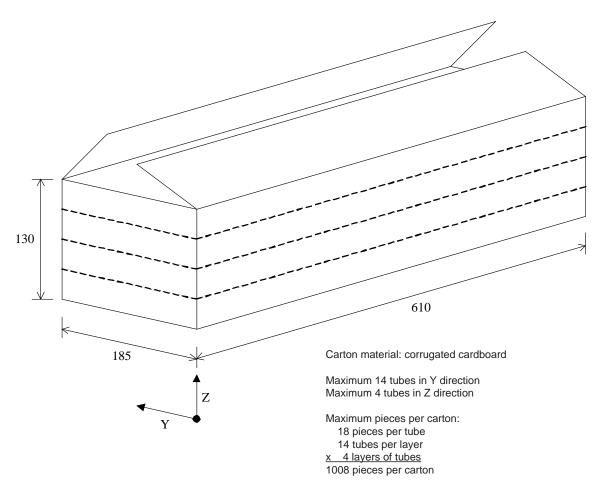




Packing Specification Leadform 2452

Dimensions in millimeters









High Voltage 3-Phase Motor Driver

WARNING — These devices are designed to be operated at lethal voltages and energy levels. Circuit designs that embody these components must conform with applicable safety requirements. Precautions must be taken to prevent accidental contact with power-line potentials. Do not connect grounded test equipment.

The use of an isolation transformer is recommended during circuit development and breadboarding.

Because reliability can be affected adversely by improper storage environments and handling methods, please observe the following cautions.

Cautions for Storage

- Ensure that storage conditions comply with the standard temperature (5°C to 35°C) and the standard relative humidity (around 40 to 75%); avoid storage locations that experience extreme changes in temperature or humidity.
- Avoid locations where dust or harmful gases are present and avoid direct sunlight.
- Reinspect for rust on leads and solderability of products that have been stored for a long time.

Cautions for Testing and Handling

When tests are carried out during inspection testing and other standard test periods, protect the products from power surges from the testing device, shorts between adjacent products, and shorts to the heatsink.

Remarks About Using Silicone Grease with a Heatsink

- When silicone grease is used in mounting this product to a heatsink, it shall be applied evenly and thinly. If more silicone grease than required is applied, it may produce stress.
- Volatile-type silicone greases may permeate the product and produce cracks after long periods of time, resulting in reduced heat radiation effect, and possibly shortening the lifetime of the product.
- Our recommended silicone greases for heat radiation purposes, which will not cause any adverse effect on the product life, are indicated in the following table:

Type	Suppliers
G746	Shin-Etsu Chemical Co., Ltd.
YG6260	Momentive Performance Materials, Inc.
SC102	Dow Corning Toray Silicone Co., Ltd.

Soldering

 When soldering the products, please be sure to minimize the working time, within the following limits:

260±5°C 10 s 380±5°C 5 s

 Soldering iron should be at a distance of at least 1.5 mm from the body of the products

Electrostatic Discharge

- When handling the products, operator must be grounded.
 Grounded wrist straps worn should have at least 1 MΩ of resistance to ground to prevent shock hazard.
- Workbenches where the products are handled should be grounded and be provided with conductive table and floor mats.
- When using measuring equipment such as a curve tracer, the equipment should be grounded.
- When soldering the products, the head of soldering irons or the solder bath must be grounded in other to prevent leak voltages generated by them from being applied to the products.
- The products should always be stored and transported in our shipping containers or conductive containers, or be wrapped in aluminum foil.





High Voltage 3-Phase Motor Driver

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